	En	colment No./Seat No	
		GUJARAT TECHNOLOGICAL UNIVERSITY BE- SEMESTER-VI (NEW) EXAMINATION – WINTER 2024	
	Su	bject Code:3161917 Date:12-12-2024	
	Su	bject Name: Computer Aided Manufacturing	
	Ti	me:02:30 PM TO 05:00 PM Total Marks:70	
	Ins	tructions:	
		1. Attempt all questions.	
		 Make suitable assumptions wherever necessary. Figures to the right indicate full marks 	
		 Figures to the right indicate run marks. Simple and non-programmable scientific calculators are allowed. 	
0.1	(-)	Define Computer Aided Manufacturing (CAM). What are its primary ship sting?	0.2
Q.1	(a) (b)	Evaluate the advantages of using PLCs over traditional hardwired control systems in terms of	US 04
	(0)	programming flexibility	04
	(c)	Identify the major components of a CIM system. Analyze the impact of CIM on production	07
	(C)	planning and control.	07
		F88	
Q.2	(a)	Define NC and CNC technology. What are the differences between them?	03
	(b)	Explain the role of sensors and actuators in a CNC system.	04
	(c)	Write a simple part program to perform a drilling operation using a CNC machine.	07
	(\mathbf{a})	OR	07
	(C)	the precision and efficiency of CNC machines?	07
		the precision and efficiency of effect machines:	
Q.3	(a)	What is a Flexible Manufacturing System (FMS)? List the key components of an FMS.	03
	(b)	Explain the concept of cellular manufacturing and how it differs from traditional batch	04
		production.	
	(c)	Explain the working principle of AS/RS and how it benefits warehouse operations.	07
03	(a)	UR List the primery objectives of implementing on FMS	03
Q.J	(a) (h)	Explain the importance of layout design in the efficiency of an FMS	03
	(c) (c)	Define Automated Guided Vehicles (AGVs). Compare the advantages and disadvantages of	07
		AGVs versus traditional material handling methods.	
Q.4	(a)	List the main functions of PPC in a manufacturing system.	03
	(b) (a)	Identify the key benefits of implementing Group Technology in manufacturing.	04
	(0)	generative CAPP systems	07
		OR	
Q.4	(a)	Explain Enterprise Resource Planning (ERP).	03
	(b)	List the steps involved in the rank order clustering method for cell design.	04
	(c)	Compare the OPITZ and PFA coding systems in terms of complexity and application with	07
		suitable example.	
Q.5	(9)	Explain the benefits of using robots in manufacturing compared to manual labor	03
	(b)	Discuss the role of JIT in inventory management and cost reduction.	04
	(c)	Explain various physical configuration of robot with example.	07
		OR	
Q.5	(a)	Explain the difference between forward kinematics and inverse kinematics in robotic motion	03
	(b)	planning.	04
	(D) (c)	Describe key components of an expert system. Define actuators and transducers in the context of robotics. Describe the role of transducers in	U4 07
		robotic sensing and feedback systems.	97
